## Hamiltonian simulation and optimal control

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7 Mar 2024

Applied and Computational Analysis (ACA) seminar
University of Cambridge

Solution of the Schrödinger equation,

$$
\mathrm{i} \partial_{t} \psi=\mathrm{H}(t) \psi, \quad \mathrm{H}(t)^{*}=\mathrm{H}(t), \quad \psi(t) \in \mathscr{H}
$$

Feynman, R. P. Simulating physics with computers. Int J Theor Phys 21, 467-488 (1982).
the real difficulty is this: If we had many particles, we have $R$ particles, for example, in a system, then we would have to describe the probability of a circumstance by giving the probability to find these particles at points $x_{1}, x_{2}, \ldots, x_{R}$ at the time $t$. That would be a description of the probability of the system. And therefore, you'd need a $k$-digit number for every configuration of the system, for every arrangement of the $R$ values of $x$. And therefore if there are $N$ points in space, we'd need $N^{R}$ configurations.
$n$-body problems

- PDE, $\psi \in \mathbb{C}^{N^{3 n}}$ after spatial discretisation with $N$ points in each direction,
- ODE, $\psi \in \mathbb{C}^{2^{n}}$ for 2 -level systems (e.g. spin systems).


## 4. QUANTUM COMPUTERS—UNIVERSAL QUANTUM SIMULATORS

The first branch, one you might call a side-remark, is, Can you do it with a new kind of computer-a quantum computer? (I'll come back to the other branch in a moment.) Now it turns out, as far as I can tell, that you can simulate this with a quantum system, with quantum computer elements.


- Linear growth in number of qubits vs exponential in classical computing
- Simple circuits with Trotterisation (no auxiliary qubits)
- Subroutine in quantum algorithms - QPE (Kitaev 95), HHL (Harrow, Hassidim, Lloyd 09)
- Every gates has underlying Hamiltonian $\Rightarrow$ every quantum circuit is HS
- A uniquely quantum phenomenon that has no classical counterpart.
- A type of intrinsic angular momentum - the particle is not rotating.
- Makes a quantum particle behave like a tiny magnet with a North pole and a South pole.


$$
\begin{gathered}
\rho=\frac{1}{2}(I+\boldsymbol{s} \cdot \boldsymbol{\sigma}) \in \mathbb{C}^{2 \times 2} \\
s \in \mathbb{R}^{3}, \\
\text { and } \boldsymbol{\sigma}=(X, Y, Z)
\end{gathered}
$$

are $2 \times 2$ Pauli matrices.

- Responsible for ferromagnetism.
- The phenomenon that powers
- magnetic resonance imaging (MRI)
- spintronics
- quantum computing
- Suspected to be involved in detection of Earth's magnetic field by birds (quantum biology).


## Quantum computing comes home

For $n$ interacting spins, state space is exponentially large, $\rho \in \mathbb{C}^{2^{n} \times 2^{n}}$.

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Resurgence of interest in quantum algorithms for Hamiltonian simulation.
Berry et al. 15, Low \& Chuang 17, 19, Low \& Wiebe 18, Smith et al. 19, Kieferova et al. 19,
Berry et al. 20, Chen et al. 21, Haah et al. 21, Jin \& Li 21, Jin et al. 21, Dong et al. 21,22, An et al. 22, Watkins et al. 22, Mizuta et al. 23,...

Hamiltonian simulation of two-level systems is among early candidates for demonstrating quantum advantage. (Childs et al. 18, Seetharam et al. 21).

Recent claim by IBM (using their Eagle processor, 14 June 2023):

- Kim, Eddins, Anand, Wei, van den Berg, Rosenblatt, Nayfeh, Wu, Zaletel, Temme \& Kandala (2023), 'Evidence for the utility of quantum computing before fault tolerance', Nature 618, 500-505.


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Used Trotter splitting for an Ising chain.

## AOTADOOOSOADO

$$
\begin{aligned}
\mathcal{H}(t) & =\underbrace{\mathrm{e}(t)^{\top} \mathbb{S}}_{\mathcal{\mathcal { H } _ { \mathrm { ss } } ( t )}}+\underbrace{\frac{1}{2} \mathbb{S}^{\top} C \mathbb{S}}_{\mathcal{H}_{\mathrm{in}}} \\
& =\sum_{k=1}^{n} \sum_{\alpha \in\{X, Y, Z\}} \mathrm{e}_{k}^{\alpha}(t) \alpha_{k}+\frac{1}{2} \sum_{j, k=1}^{n} \sum_{\alpha, \beta \in\{X, Y, Z\}} C_{j, k}^{\alpha, \beta} \alpha_{j} \beta_{k}
\end{aligned}
$$

where $\alpha_{k}$ acts on $k$ th spin only,

$$
\alpha_{k}=\underbrace{I \otimes \cdots \otimes I}_{n-k \text { times }} \otimes \underbrace{\alpha}_{k \text { th }} \otimes \underbrace{I \otimes \cdots \otimes I}_{k-1 \text { times }} \in \mathbb{C}^{2^{n} \times 2^{n}},
$$

and $\alpha=X, Y, Z$ are Pauli matrices,

$$
X=\left(\begin{array}{cc}
0 & 1 \\
1 & 0
\end{array}\right), \quad Y=\left(\begin{array}{cc}
0 & -\mathrm{i} \\
\mathrm{i} & 0
\end{array}\right), \quad Z=\left(\begin{array}{cc}
1 & 0 \\
0 & -1
\end{array}\right)
$$

Two-level systems: Ising chains, Kitaev models, NMR/ESR, qubits (spin, superconducting, ...)

## Time-independent Hamiltonian - classical Trotterisation algorithms

$$
\partial_{t} u=\mathcal{A} u, \quad u(0)=u_{0}
$$

exact solution given by matrix exponential

$$
u(t)=\exp (t \mathcal{A}) u_{0}=\sum_{k=0}^{\infty} \frac{(t \mathcal{A})^{k}}{k!} u_{0}
$$

Hamiltonian simulation:

$$
\begin{equation*}
\mathcal{A}=-\mathrm{i} h\left(\mathrm{e}^{\top} \mathbb{S}+\frac{1}{2} \mathbb{S}^{\top} C \mathbb{S}\right) \tag{1}
\end{equation*}
$$

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$$

For non-interacting spins, since $\mathfrak{s u}(2)$ is spanned by $\mathrm{i} X, \mathrm{i} Y, \mathrm{i} Z$ and

$$
[X, Y]=\mathrm{i} Z, \quad[Y, Z]=\mathrm{i} X, \quad[Z, X]=\mathrm{i} Y
$$

can compute exponential analytically
$\mathrm{e}^{t \mathcal{A}}=\bigotimes_{k=1}^{n} \mathrm{e}^{-\mathrm{i} t \boldsymbol{e}_{k} \cdot \boldsymbol{\sigma}}=\bigotimes_{k=1}^{n}\left(\begin{array}{cc}\cos \left(\frac{t\left\|\boldsymbol{e}_{k}\right\|}{2}\right)-\mathrm{i} e_{k}^{2} \frac{\sin \left(\frac{\left\|\boldsymbol{e}_{k}\right\|}{2}\right)}{\left\|t \boldsymbol{e}_{k}\right\|} & \left(-\mathrm{i} e_{k}^{x}-e_{k}^{y}\right) \frac{\sin \left(\frac{t\left\|\boldsymbol{e}_{k}\right\|}{2}\right)}{\left\|\boldsymbol{e}_{k}\right\|} \\ \left(-\mathrm{i} e_{k}^{x}+e_{k}^{y}\right) \frac{\sin \left(\frac{t\left\|\boldsymbol{e}_{k}\right\|}{2}\right)}{\left\|\boldsymbol{e}_{k}\right\|} & \cos \left(\frac{t\left\|\boldsymbol{e}_{k}\right\|}{2}\right)+\mathrm{i} \mathrm{e}_{k}^{z} \frac{\sin \left(\frac{t\left\|\boldsymbol{e}_{k}\right\|}{2}\right)}{\left\|\boldsymbol{e}_{k}\right\|}\end{array}\right)$,

$$
\partial_{t} u=\mathcal{A} u, \quad u(0)=u_{0}
$$

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$$
u(t)=\exp (t \mathcal{A}) u_{0}=\sum_{k=0}^{\infty} \frac{(t \mathcal{A})^{k}}{k!} u_{0}
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\cos \left(\frac{t\left\|\boldsymbol{e}_{k}\right\|}{2}\right)-\mathrm{ie} e_{k}^{\sin \left(\frac{\left\|\boldsymbol{e}_{k}\right\|}{2}\right)}\left\|t \boldsymbol{e}_{k}\right\| & \left(-\mathrm{i} e_{k}^{\times}-e_{k}^{y}\right) \frac{\sin \left(\frac{t\left\|\boldsymbol{e}_{k}\right\|}{2}\right)}{\left\|\boldsymbol{e}_{k}\right\|} \\
\left(-\mathrm{i} e_{k}^{\times}+e_{k}^{y}\right) \frac{\sin \left(\frac{t\left\|\boldsymbol{e}_{k}\right\|}{2}\right)^{2}}{\left\|\boldsymbol{e}_{k}\right\|} & \cos \left(\frac{t\left\|\boldsymbol{e}_{k}\right\|}{2}\right)+\mathrm{i} \mathrm{i}_{k}^{z} \frac{\sin \left(\frac{t\left\|\boldsymbol{e}_{k}\right\|}{\left\|\boldsymbol{e}_{k}\right\|}\right.}{2}
\end{array}\right)
$$

Trotterisation: For $-\mathrm{iH}=A+B$ we need to split

$$
\exp (h(A+B))=\mathrm{e}^{h A} \mathrm{e}^{h B}+\mathcal{O}\left(h^{2}\right)
$$

Trotterisation:

$$
\mathrm{e}^{-\mathrm{i} h\left(\mathcal{H}^{X}+\mathcal{H}^{Y}+\mathcal{H}^{z}\right)}=\mathrm{e}^{-\mathrm{i} h \mathcal{H}^{X}} \mathrm{e}^{-\mathrm{i} h \mathcal{H}^{Y}} \mathrm{e}^{-\mathrm{i} h \mathcal{H}^{z}}+\mathcal{O}\left(h^{2}\right),
$$

where

$$
\mathcal{H}^{\alpha}=\mathbf{e}^{\top} \mathbb{S}^{\alpha}+\frac{1}{2} \mathbb{S}^{\alpha \top} C^{\alpha, \alpha} \mathbb{S}^{\alpha}, \quad \alpha \in\{X, Y, Z\}
$$

and

$$
\mathrm{e}^{-\mathrm{i} h \mathcal{H}^{\alpha}}=\prod_{\ell=1}^{n} \mathrm{e}^{-\mathrm{i} h e_{\ell}^{\alpha} \alpha_{\ell}} \prod_{j=1}^{n} \prod_{k=j+1}^{n} \mathrm{e}^{-\mathrm{i} h c_{j, k}^{\alpha, \alpha} \alpha_{j} \alpha_{k}}
$$

computed exactly using $n$ single-qubit gates and $\mathcal{O}\left(n^{2}\right)$ coupling gates.


## Trotterisation $\leftrightarrow$ Splitting methods for matrix exponential

If $\mathrm{e}^{h A}$ and $\mathrm{e}^{h B}$ are easier to compute, approximate $\mathrm{e}^{h(A+B)}$ by

| splitting | error | name | stages |
| :--- | :--- | :--- | :--- |
| $\mathrm{e}^{h A} \mathrm{e}^{h B}$ | $\mathcal{O}\left(h^{2}\right)$ | Trotter | 2 |

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| $\mathrm{e}^{h A} \mathrm{e}^{h B}$ | $\mathcal{O}\left(h^{2}\right)$ | Trotter | 2 |
| $\mathrm{e}^{\frac{1}{2} h B} \mathrm{e}^{h A} \mathrm{e}^{\frac{1}{2} h B}$ | $\mathcal{O}\left(h^{3}\right)$ | Strang | 3 |
| $\mathrm{e}^{\mathrm{a}_{1} h B} \mathrm{e}^{b_{1} h A} \mathrm{e}^{a_{2} h B} \ldots \mathrm{e}^{b_{h} h A} \ldots \mathrm{e}^{\mathrm{a}_{2} h B} \mathrm{e}^{b_{1} h A} \mathrm{e}^{a_{1} h B}$ | $\mathcal{O}\left(h^{2 p+1}\right)$ | Classical | $\mathcal{O}\left(2^{p}\right)$ |
| $\mathrm{e}^{\frac{h}{6} A} \mathrm{e}^{\frac{h}{2} B} \mathrm{e}^{\frac{2}{3}\left(h A+\frac{h^{3}}{4}[[A, B], B]\right)} \mathrm{e}^{\frac{h}{2} B} \mathrm{e}^{\frac{h}{6} A}$ | $\mathcal{O}\left(h^{2 p+1}\right)$ | Compact | $\mathcal{O}\left(2^{p}\right)$ |
| $\mathrm{e}^{\frac{h}{2} B} \mathrm{e}^{\frac{h}{2} A} \mathrm{e}^{h^{3} R} \mathrm{e}^{h^{5} S} \mathrm{e}^{h^{3} R} \mathrm{e}^{\frac{h}{2} A} \mathrm{e}^{\frac{h}{2} B}$ | $\mathcal{O}\left(h^{2 p+1}\right)$ | Asymptotic | $\mathcal{O}(p)$ |

[^0]
## High order splittings



No good reason to use Trotter instead of Strang, even for NISQ Chen, Foroozandeh, Budd \& S. 2023. Quantum simulation of highly-oscillatory many-body Hamiltonians for near-term devices, submitted

## Quantum advantage in NISQ era?

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## Dulwich Quantum Computing

@DulwichQuantum
At least 7 articles so far have reproduced the @IBM computation classically:
arxiv.org/abs/2306.14887
arxiv.org/abs/2306.15970
arxiv.org/abs/2306.16372
arxiv.org/abs/2308.01339
arxiv.org/abs/2308.03082
arxiv.org/abs/2308.05077
arxiv.org/abs/2308.09109
6:19 PM • Aug 21, $2023 \cdot 17.3 \mathrm{~K}$ Views

## What should we expect from quantum Hamiltonian simulation?

BQP (bounded-error quantum polynomial time)
Class of decision problems solvable by a quantum computer in polynomial time, with an error probability of at most $1 / 3$ for all instances.

$$
\mathrm{P} \subseteq \mathrm{BQP} \subseteq \mathrm{PSPACE}
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$$
\mathrm{P} \stackrel{?}{=} \mathrm{BQP} \stackrel{?}{=} \mathrm{PSPACE} \quad \text { is not known. }
$$

The only 'definitive' proof of quantum 'supremacy' (in Hamiltonian simulation or otherwise) is to show BQP $\neq \mathrm{P}$.


## Computing the matrix exponential

C. Moler \& C. V. Loan, Nineteen Dubious Ways to Compute the Exponential of a Matrix, Twenty-Five Years Later, SIAM Review (2003).

Splitting, Diagonalisation, Scaling and Squaring

|  | Asymptotic <br> $z \rightarrow 0$ | Approximate $\mathrm{e}^{z}$ on spectrum <br> $z \in[a, b] \subseteq \sigma(A)$ | Iterative <br> Use $A$ and $u_{0}$ |
| :--- | :---: | :---: | :---: |
| Polynomial | Taylor <br> $\sum_{k=0}^{n} \frac{z^{k}}{k!}$ | $J_{0}(\mathrm{i})+2 \sum_{k=1}^{n} \mathrm{i}^{k} J_{k}(-\mathrm{i}) T_{k}(z)$ | Lanczos |
| Rational | Padé <br> $1+\frac{1}{2} z+\frac{1}{12} z^{2}$ <br> $1-\frac{1}{2} z+\frac{1}{12} z^{2}$ | $?$ | Rational Krylov |

Qubitization (Low \& Chuang 2019) based on Chebyshev.

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Unitarity: $|\exp (\mathrm{ix})|=1, \exp$ maps imaginary axis to unit circle.

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Unitarity: $|\exp (i x)|=1$, exp maps imaginary axis to unit circle.
Since $\sigma(\mathrm{iH}) \subseteq i \mathbb{R}$,

$$
|f(\mathrm{ix} x)|=1 \quad x \in \mathbb{R} \quad \Longrightarrow \quad f(\mathrm{iH}) \text { is unitary }
$$

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$$

No non-constant polynomial method can be unitary. Proof: coercivity.

## Why care about unitarity?

Schrödinger equation

$$
\begin{aligned}
& \partial_{t} u=-\mathrm{iH} u, \quad u(0)=u_{0}, \quad \mathrm{H}^{*}=\mathrm{H}, \\
& u(t)=e^{-i t H} u_{0} \\
& E(t):=\langle u(t), \mathrm{H} u(t)\rangle \quad=\quad\langle u(0), \mathrm{H} u(0)\rangle=E(0) \quad \text { energy conservation } \\
& \underbrace{\langle u(t), v(t)\rangle=\langle u(0), v(0)\rangle}_{\text {unitary evolution }} \Longrightarrow \underbrace{\|u(t)\|_{2}=\|u(0)\|_{2}=1}_{\text {mass or probability conservation }}
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$$

exp maps Lie algebra $\mathrm{iH} \in \mathfrak{s u}(n)$ to Lie group $\mathrm{e}^{-\mathrm{i} t \mathrm{H}} \in \mathrm{U}(n)$.

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These properties are also desired from numerical approximations.

$$
\begin{array}{lrlrl}
\mathrm{e}^{z} \approx 1+z & u_{1} & = & (I-\mathrm{i} h \mathrm{H}) u_{0} & \text { F.E. } \\
\mathrm{e}^{z} \approx \frac{1}{1-z} & (I+\mathrm{i} h \mathrm{H}) u_{1} & =u_{n} \|_{2} \rightarrow \infty \\
\mathrm{e}^{z} \approx \frac{1+z / 2}{1-z / 2} & (I+\mathrm{i}(h / 2) \mathrm{H}) u_{1} & = & (I-\mathrm{i}(h / 2) \mathrm{H}) u_{0} & \text { B.E. } \quad\left\|u_{n}\right\|_{2} \rightarrow 0 \\
\operatorname{cay}(z)=\frac{1+z / 2}{1-z / 2} & \text { maps Lie algebra } \mathrm{iH} & \in \mathfrak{s u}(n) \text { to Lie group } \mathrm{e}^{-\mathrm{i} t \mathrm{H}} \in \mathrm{U}(n) .
\end{array}
$$

Wave, KdV, NLS, Pauli, Dirac, Liouville-von Neumann, Linblad, MCTDHF, CCSD, TDDFT, . .

## Uniform approximation with AAA \& AAA-Lawson

- AAA. Nakatsukasa, Sète \& Trefethen. The AAA algorithm for rational approximation, SIAM J. Sci. Comput., Vol. 40, Iss. 3 (2018).
- AAA-Lawson. Nakatsukasa \& Trefethen. An algorithm for real and complex rational minimax approximation, SIAM J. Sci. Comput., Vol. 4, Iss. 5 (2020).

Error in approximation of $\mathrm{e}^{\mathrm{ix}}$
(Padé vs AAA-Lawson)


AAA and AAA-Lawson methods are adaptive algorithms that can produce rational approximants with uniform accuracy over a specified interval or test nodes $x_{k}$.

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$$
r(x)=\underbrace{\sum_{j=1}^{m} \frac{\mathrm{e}^{\mathrm{i} y_{j}} w_{j}}{x-y_{j}}}_{n(x)} / \underbrace{\sum_{j=1}^{m} \frac{w_{j}}{x-y_{j}}}_{d(x)} \approx \mathrm{e}^{\mathrm{i} x}
$$

linearize and minimize

$$
\|L w\|_{2}=\left(\sum_{k=1}^{n} \mu_{k}\left|n\left(x_{k}\right)-\mathrm{e}^{\mathrm{i} x_{k}} d\left(x_{k}\right)\right|^{2}\right)^{1 / 2}
$$

Computed using SVD of Loewner matrix, $L_{k j}=\mu_{k}^{1 / 2} \frac{\mathrm{e}^{\mathrm{i} x_{k}}-\mathrm{e}^{\mathrm{i} y_{j}}}{x_{k}-y_{j}}$, and picking $w$ as the right singular vector corresponding to the smallest singular value.

## Unitarity of AAA \& AAA-Lawson

Loewner matrix based rational approximations and interpolations are unitary. Jawecki \& S 2023. Unitarity of some barycentric rational approximants, IMA J. Num. Anal. Includes Antoulas \& Anderson 1986, Mayo \& Antoulas 2007, NST 2018 (AAA), NT 2020 (AAA-Lawson), JS (submitted) (interpolation at Chebyshev nodes, modified BRASIL algorithm, modified AAA-Lawson), ...

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Jawecki \& S 2023. Unitarity of some barycentric rational approximants, IMA J. Num. Anal.

Includes Antoulas \& Anderson 1986, Mayo \& Antoulas 2007, NST 2018 (AAA), NT 2020 (AAA-Lawson), JS
(submitted) (interpolation at Chebyshev nodes, modified BRASIL algorithm, modified AAA-Lawson), ...


Modified AAA and AAA-Lawson (JS 23) ensures unitarity to machine precision.

## Non-uniform and split spectrum approximation

Wavefunction centred around two different energy levels

$$
u_{0}(x)=\psi_{1}(x)+\psi_{2}(x), \quad \psi_{j}(x)=\sum_{k=0}^{n} c_{j, k} v_{k}(x), \quad c_{j, k}=\mathrm{e}^{-\left(\mu_{j}-\lambda_{k}\right)^{2} / 2 \sigma_{j}^{2}}
$$

Error in approximation of $\mathrm{e}^{\mathrm{i} x}$
(AAA-Lawson)


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Error in approximation of $\mathrm{e}^{\mathrm{i} x}$ (AAA-Lawson)

Error in matrix approximation $r(-\mathrm{i} h \mathrm{H}) u_{0}$ $((31,31)$ AAA-Lawson vs Padé $)$



Jawecki \& S. in preparation

## Best approximation

Approximating $f \in \mathrm{C}([a, b] ; \mathbb{R})$ in $\mathcal{P}_{n}[a, b]$

- Best approximant $p^{*} \in \mathcal{P}_{n}$ exists \& unique

$$
\left\|f-p^{*}\right\|_{\infty}=\inf \left\{\|f-p\|_{\infty}: p \in \mathcal{P}_{n}\right\}
$$

- Chebyshev equioscillation theorem

$$
f\left(x_{j}\right)-p^{*}\left(x_{j}\right)=(-1)^{j+\iota}\|f-p\|_{\infty}, \quad \iota \in\{0,1\}
$$

- Remez minimax algorithm
- Find points $\left\{x_{j}\right\}$ of local maximum error $\left|f(x)-p^{[k]}(x)\right|$.
- Stop if equioscillation property satisfied.
- Otherwise, solve for $f\left(x_{j}\right)-p^{[k+1]}\left(x_{j}\right)=(-1)^{j} E$

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Motivates AAA-Lawson minimax algorithm [NT20] for approximating $f \in \mathrm{C}(I \subseteq \mathbb{C} ; \mathbb{C})$ in $\mathcal{R}_{n}[I]=\left\{\frac{p}{q}: p, q \in \mathcal{P}_{n}\right\}$ (or in Barycentric forms).

- Gives good approximants in practice (typically), but ...

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- Gives good approximants in practice (typically), but ...
- No best approximation results for complex-valued rational approximation,
- $\left\{p \in \mathcal{P}_{n}:\|p\|_{\infty}=1\right\}$ is compact, $\left\{r \in \mathcal{R}_{n}:\|r\|_{\infty}=1\right\}$ is not compact,
- No equioscillation property in $\mathbb{C}$.


## Equioscillation

Figures from [NT20]
(left) $f(z)=\mathrm{e}^{z}$ on $\{z \in \mathbb{C}:|z|=1\}$ (right) $f(z)=\operatorname{Ai}(z)$ on $z \in[-10,10]$
deviation $f(z)-r(z) \&$ max error $\|f-r\|$
No equioscillation!



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$$
f(\mathrm{i} x)=\mathrm{e}^{\mathrm{i} \omega x}, \quad x \in[-1,1]
$$

18 June (left), T. Jawecki
28 June (right), N. Trefethen
Rose curves with $2 n$ petals. equioscillation?


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Let $r(\mathrm{i} x)=\mathrm{e}^{\mathrm{i} g(x)}$, where $g(x)$ is phase Optimality $\Longleftrightarrow$ phase equioscillates
$g\left(x_{j}\right)-\omega x_{j}=(-1)^{j+\iota} \max _{x \in[-1,1]}|g(x)-\omega x|$.
$\left|r\left(\mathrm{i} x_{j}\right)-\mathrm{e}^{\mathrm{i} \omega x_{j}}\right|=\|r-\exp (\omega \cdot)\|$
Zeros of phase \& approx error coincide.



## Best (unitary rational) approximation

Jawecki \& S 2023. Unitary rational best approximations to the exponential function, submitted.
Theorem. For $\omega \in(0,(n+1) \pi)$, there exists a unique unitary best approximation $r \in \mathcal{U}_{n}$, i.e.,

$$
\|r-\exp (\omega \cdot)\|=\inf _{u \in \mathcal{U}_{n}}\|u-\exp (\omega \cdot)\|, \quad\|f\|:=\sup _{x \in[-1,1]}|f(\mathrm{ix})|,
$$

whose phase error equioscillates at $2 n+2$ points, where max approx error is achieved. Moreover, $r$ has minimal degree $n$, and distinct poles.

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Superlinear convergence. For $\omega<1.47(n+1 / 2)$,

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\min _{u \in \mathcal{U}_{n}}\|u-\exp (\omega \cdot)\| \leq \frac{(n!)^{2} \omega^{2 n+1}}{(2 n)!(2 n+1)!}
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(proof via Pad́e),

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$$

(proof via Pade), and in the limit $\omega \rightarrow 0^{+}$,

$$
\min _{u \in \mathcal{U}_{n}}\|u-\exp (\omega \cdot)\|=\frac{2(n!)^{2}}{(2 n)!(2 n+1)!}\left(\frac{\omega}{2}\right)^{2 n+1}+\mathcal{O}\left(\omega^{2 n+2}\right), \quad \omega \rightarrow 0^{+}
$$

(proof via interpolation at Chebyshev points), twice as fast as Padé.

## Poles, $\omega \rightarrow 0^{+}, \omega \rightarrow(n+1) \pi^{-}$



In the limit $\omega \rightarrow 0^{+}$, poles converge to poles of Padé.
In the limit $\omega \rightarrow(n+1) \pi^{-}$, poles approach $\mathrm{i} \xi_{j}$, where $\xi_{j}=-1+2 j /(n+1)$ for $j=1, \ldots, n$, within the right-half complex plane.

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A-stability. Poles of best approximants are in right half plane and

$$
|r(z)|<1, \quad \text { for } z \in \mathbb{C} \text { with } \operatorname{Re}(z)<0
$$

Relevant for non-Hermitian matrices/operators (e.g. open systems).
Time-symmetric.

$$
r(-\mathrm{i} x)=r(\mathrm{i} x)^{-1}, \quad x \in \mathbb{R}
$$

## Interpolation and equioscillation points, $\omega \rightarrow 0^{+}, \omega \rightarrow(n+1) \pi^{-}$



In the limit $\omega \rightarrow 0^{+}$, interpolation points converge to Chebyshev nodes.
In the limit $\omega \rightarrow(n+1) \pi^{-}$, interpolation points and equioscillation points converge to uniformly distributed points. Phase error approaches sawtooth function.

Three new algorithms. Interpolation at Chebyshev points, modified AAA-Lawson and BRASIL algorithms - latter two candidates for best approximation (seem to display equioscillatory behaviour).


Figure 1: [new] unitary best approximation (■), error estimate (dashed, + ), [new] rational interpolant at Chebyshev nodes $(\triangleright)$, Padé approximation ( $\circ$ ), Padé error bound (dashed, $\times$ ), polynomial Chebyshev approximation $(\nabla)$, rational Chebyshev approximation $(\triangle)$, .

## How to compute the matrix exponential?

C. Moler \& C. V. Loan, Nineteen Dubious Ways to Compute the Exponential of a Matrix, Twenty-Five Years Later, SIAM Review (2003).

|  | Asymptotic <br> $z \rightarrow 0$ | Approximate $\mathrm{e}^{z}$ on spectrum <br> $z \in[a, b] \subseteq \sigma(A)$ | Iterative <br> Polynomial |
| :---: | :---: | :---: | :---: |
| $\sum_{k=0}^{n} \frac{z^{k}}{k!}$ | $J_{0}(\mathrm{i})+2 \sum_{k=1}^{n} \mathrm{i}^{k} J_{k}(-\mathrm{i}) T_{k}(z)$ | Use $A$ and $u_{0}$ |  |
| Rational | $\frac{1+\frac{1}{2} z+\frac{1}{12} z^{2}}{1-\frac{1}{2} z+\frac{1}{12} z^{2}}$ | unitary best approximations | Rational Krylov |
| Paylor |  |  |  |

Other techniques: Diagonalisation, Spectral methods, Scaling and Squaring, Splitting
AAA [NST 18], AAA-Lawson [NT 20], their unitary modifications [JS 23], and three new algorithms [JS submitted].

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## Driven systems - Is Magnus expansion DoA?

The solution to $u^{\prime}(t)=\mathcal{A}(t) u(t), \quad \mathcal{A}(t)=-\mathrm{iH}(t)$,

$$
u(h)=\exp (\Theta(h)) u_{0}
$$

where $\Theta(h)$ is the Magnus expansion [Magnus 54],

$$
\begin{aligned}
& \Theta(h)= \int_{0}^{h} \mathcal{A}(\xi) \mathrm{d} \xi-\frac{1}{2} \int_{0}^{h} \int_{0}^{\xi}[\mathcal{A}(\zeta), \mathcal{A}(\xi)] \mathrm{d} \zeta \mathrm{~d} \xi \longleftarrow \text { Fourth order } \\
&+\frac{1}{12} \int_{0}^{h} \int_{0}^{\xi} \int_{0}^{\xi}[\mathcal{A}(\chi),[\mathcal{A}(\zeta), \mathcal{A}(\xi)]] \mathrm{d} \chi \mathrm{~d} \zeta \mathrm{~d} \xi \\
&+\frac{1}{4} \int_{0}^{h} \int_{0}^{\xi} \int_{0}^{\zeta}[[\mathcal{A}(\chi), \mathcal{A}(\zeta)], \mathcal{A}(\xi)] \mathrm{d} \chi \mathrm{~d} \zeta \mathrm{~d} \xi+\ldots \\
& \mathcal{A}(t)=-\mathrm{iH}(t), \quad \mathrm{H}(t)=\underbrace{\sum_{k=1}^{n} \sum_{\alpha \in\{X, Y, Z\}} \mathrm{e}_{k}^{\alpha}(t)}_{\mathcal{O}(n) \text { terms }} \alpha_{k}+\underbrace{\frac{1}{2} \sum_{j, k=1}^{n} \sum_{\alpha, \beta \in\{X, Y, Z\}} C_{j, k}^{\alpha, \beta} \alpha_{j} \beta_{k}}_{|\mathcal{C}| \leq \mathcal{O}\left(n^{2}\right) \text { terms }}
\end{aligned}
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& \mathcal{A}(t)=-\mathrm{i} H(t), \quad \mathrm{H}(t)=\underbrace{\sum_{k=1}^{n} \sum_{\alpha \in\{X, Y, Z\}} \mathrm{e}_{k}^{\alpha}(t)}_{\mathcal{O}(n) \text { terms }} \alpha_{k}+\underbrace{\frac{1}{2} \sum_{j, k=1}^{n} \sum_{\alpha, \beta \in\{X, Y, Z\}} C_{j, k}^{\alpha, \beta} \alpha_{j} \beta_{k}}_{|C| \leq \mathcal{O}\left(n^{2}\right) \text { terms }}
\end{aligned}
$$

Issue: $\mathcal{A}$ has $\mathcal{O}(|C|)=\mathcal{O}\left(n^{2}\right)$ terms. Does $\Theta_{2}$ have $\mathcal{O}\left(|C|^{2}\right)=\mathcal{O}\left(n^{4}\right)$ terms?
A standard method for classical computers, infeasible for quantum computers.
Instead, other approaches used: Dyson series (Kieferova et al. 2019), time-ordered operators (Watkins et al. 2022),
L1 norm scaling (Berry et al. 2020), permutation expansion (Chen et al. 2021), slowly varying Hamiltonians (Haah et al. 2021), interaction picture (Low \& Wiebe 2018), Floquet approach (Mizuta et al. 2023).

## Driven systems - Is Magnus expansion DoA? No!

Theorem (Fourth order Magnus based circuit)


$$
\underbrace{\mathrm{e}^{-\mathrm{i} \frac{2}{h} \mathbf{u}^{\top} \mathrm{S}}}_{\text {single-gate layers }}=\mathrm{e}^{\Theta_{2}}+\mathcal{O}\left(h^{5}\right)
$$

Chen, Foroozandeh, Budd \& S. 2023. submitted
For two controls: Ikeda, Abrar, Chuang \& Sugiura 2023. Quantum.


In fact, Magnus is much better than all other methods!
Time-dependent problems of practical interest are MUCH harder!

## Driven systems - optimal control

Maximize fidelity:

$$
\theta^{*}=\underset{\theta}{\operatorname{argmax}} \mathcal{F}(\theta)
$$

Fidelity functions

$$
\mathcal{F}(\theta)=f(\mathbf{U}(T ; \theta))
$$

where state of system is $\rho(t)=\mathbf{U}(t ; \theta) \rho_{0}$.

state-to-state

$$
f(X)=\operatorname{Re}\left[\operatorname{Tr}\left(\varrho^{\dagger} X \rho_{0}\right)\right]
$$



$$
\begin{gathered}
\text { gate design } \\
f(X)=\operatorname{Re}\left[\operatorname{Tr}\left(\mathbf{U}_{\text {target }}^{\dagger} X\right)\right]
\end{gathered}
$$

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gate design

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$$

Local optimization: need gradients

$$
\frac{\partial \mathcal{F}}{\partial \theta}=\mathbf{D} f(\mathbf{U}(T ; \theta)) \frac{\partial \mathbf{U}(T ; \theta)}{\partial \theta}
$$

and Hessians.

## Analytic gradients - uncoupled

- No dissipation
- Piecewise constant

$$
\mathbf{U}(T ; \theta)=\mathrm{U}_{N} \mathrm{U}_{N-1} \cdots \mathrm{U}_{2} \mathrm{U}_{1}, \quad \text { with } \quad \mathrm{U}_{n}=\mathrm{e}^{-\mathrm{i} \boldsymbol{s}_{n} \cdot \boldsymbol{\sigma}}, \quad \boldsymbol{s}_{n}:=h \boldsymbol{e}\left(t_{n}\right)
$$

We can store intermediate propagators

$$
\mathrm{L}_{n}:=\mathrm{U}_{N} \mathrm{U}_{N-1} \ldots \mathrm{U}_{n}, \quad \mathrm{R}_{n}:=\mathrm{U}_{n} \mathrm{U}_{n-1} \ldots \mathrm{U}_{1}, \quad \mathcal{O}(N)
$$

to compute gradients cheaply and exactly

$$
\begin{gathered}
\frac{\partial \mathbf{U}}{\partial \theta_{n, k}}=\mathrm{L}_{n+1} \frac{\partial \mathrm{U}_{n}}{\partial \theta_{n, k}} \mathrm{R}_{n-1}, \quad \frac{\partial \mathrm{U}_{n}}{\partial \theta_{n, k}}=-\mathrm{i} \mathrm{U}_{n}\left(\left[\boldsymbol{D}_{n} \frac{\partial \boldsymbol{s}_{n}}{\partial \theta_{n, k}}\right] \cdot \sigma\right), \\
\boldsymbol{D}_{n}=\sum_{p=0}^{\infty} \frac{\left(-\boldsymbol{s}_{n}\right)^{p}}{(p+1)!}=1+c_{1} \boldsymbol{s}_{n}+c_{2} \boldsymbol{s}_{n}^{2}, \quad \boldsymbol{s}_{n}=\left(\begin{array}{ccc}
0 & -s_{n, z} & s_{n, y} \\
s_{n, z} & 0 & -s_{n, x} \\
-s_{n, y} & s_{n, x} & 0
\end{array}\right) .
\end{gathered}
$$

## Analytic Hessian - uncoupled

The typical approach for computing the Hessian involves computing and storing

$$
\mathrm{M}_{n, m}:=\mathrm{U}_{n} \mathrm{U}_{n-1} \ldots \mathrm{U}_{m+1} \mathrm{U}_{m} . \quad \mathcal{O}\left(N^{2}\right)
$$

and use for computing $\frac{\partial^{2} U}{\partial \theta_{m, j} \partial \theta_{n, k}}=\mathrm{L}_{n+1} \frac{\partial \mathrm{U}_{n}}{\partial \theta_{n, k}} \mathrm{M}_{n-1, m+1} \frac{\partial \mathrm{U}_{m}}{\partial \theta_{m, j}} \mathrm{R}_{m-1}$.

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$$
\mathrm{M}_{n, m}=\left(\mathrm{U}_{N} \ldots \mathrm{U}_{n+1}\right)^{*} \mathrm{U}_{N} \ldots \mathrm{U}_{n+1} \mathrm{M}_{n, m} \mathrm{U}_{m-1} \ldots \mathrm{U}_{1}\left(\mathrm{U}_{m-1} \ldots \mathrm{U}_{1}\right)^{*}
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$$

so that entries of the Hessian can be computed as $\mathrm{L}_{n+1} \frac{\partial \mathrm{U}_{n}}{\partial \theta_{n, k}} \mathrm{~L}_{n}^{*} \mathrm{UR}_{m}^{*} \frac{\partial \mathrm{U}_{m}}{\partial \theta_{m, j}} \mathrm{R}_{m-1}$.

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Speedup: $\times 2-10$ fidelity, $\times 4-30$ gradient, $\times 20-600$ Hessian.
Foroozandeh \& S. 2022. Automatica. ESCALADE doi:10.17632/8zz84359m5
Goodwin \& Vinding 2023. Phys. Rev. Res.

## Coupling, dissipation \& adaptive optimal control

Liouville-von Neumann equation, piecewise constant,

$$
\partial_{t} \rho=\mathcal{L}(t ; \theta) \rho, \quad \mathcal{L}_{n}(\theta)=\underbrace{-\operatorname{iad}_{\mathrm{e}\left(t_{n} ; \theta\right)^{\top} \mathbb{S}}}_{\mathcal{L}_{n}^{[1]}(\theta)} \underbrace{-\mathrm{iad}_{\mathrm{H}_{\mathrm{in}}+\mathcal{R}}}_{\mathcal{L}^{[2]}}
$$

Splittings $\mathcal{S}_{(1)}, \mathcal{S}_{(2)}, \ldots, \mathcal{S}_{(L)} \approx \mathbf{U}(T ; \theta)$ with increasing accuracies,

$$
\mathrm{U}_{n}=\mathrm{e}^{h \mathcal{L}_{n}(\theta)} \approx \prod_{k=1}^{K} \underbrace{\mathrm{e}^{h a_{k} \mathcal{L}_{n}^{[1]}(\theta)}}_{\text {uncoupled, analytic grad }} \mathrm{e}^{h b_{k} \mathcal{L}^{[2]}}
$$

Move from $\mathcal{S}_{(\ell)}$ to $\mathcal{S}_{(\ell+1)}$ when $\left|\mathcal{F}_{(\ell)}-\mathcal{F}_{(\ell+1)}\right| \leq \kappa_{\mathcal{F}}\left|1-\mathcal{F}_{(\ell)}\right|$


Goodwin, Foroozandeh \& S. 2022. Science Advances. QOALA github.com/superego101/qoala

## Takeaways \& Open Problems

- Quantum Computing. [1] Chen, Foroozandeh, Budd \& S. 2023. Quantum simulation of highly-oscillatory many-body Hamiltonians for near-term devices, submitted
- No good reason to use Trotter (used in IBM paper) instead of Strang.
- Practical time-dependent problems are much harder, high order methods required.
- Magnus methods are not DoA, in fact, lead to shortest circuits even for $10^{-1}$ accuracy.
-     * Better splittings? Better commutator-free methods?
- Approximation Theory. [2] Jawecki \& S. 2023. Unitarity of some barycentric rational approximants, IMA J. Num. Anal. [3] Jawecki \& S. 2023. Unitary rational best approximations to the exponential function, submitted. [4] Jawecki \& S., in prep.
- Loewner based algorithms (incl. AAA) conserve unitarity, energy, norm
- Unitary rational best approximations exist, unique \& phase equioscillates
- Three new algorithms (Cheb. interp., AAA-Lawson at Cheb., modified BRASIL), AAA/AAA-Lawson, all superior to existing rational approximations.
-     * Rational best approximations to $\mathrm{e}^{\mathrm{i} \omega x}=$ Unitary rational best approximations?
-     * Observed twice faster convergence than Padé. Proof for non-asymptotic $\omega$ ?
-     * Does modified BRASIL converge to best approximation?
- Optimal Control. [5] Foroozandeh \& S. 2022. Optimal control of spins by Analytical Lie Algebraic Derivatives, Automatica. ESCALADE doi:10.17632/8zz84359m5. [6] Goodwin, Foroozandeh \& S. 2022. Adaptive optimal control of entangled qubits, Science Advances. QOALA github.com/superego101/qoala. [7] Sherzad, Chen, Foroozandeh \& S., in prep.
- Compute analytic gradients using Lie algebraic techniques.
- Hessian factorization reduces cost from $\mathcal{O}\left(N^{2}\right)$ to $\mathcal{O}(N), x 20-600$ speedup.
- Use cheaper method far from optima, switch adaptively.
-     * Are pulses robust under timing and amplitude imperfections?


## Temporary page!

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If you rerun the document (without altering it) this surplus page will go aw because $A$ TTEX now knows how many pages to expect for this document.


[^0]:    Yoshida 1990, Murua \& Sanz-Serna 1999, Chin \& Chen 2002, McLachlan \& Quispel 2002, Blanes, Casas \& Murua 2008, Chartier \&
    Murua 2009, ... Asymptotic (Zassenhaus) Bader, Iserles, Kropielnicka, \& S. 2014, Found. Comp. Math.

