## Hamiltonian simulation and optimal control

Pranav Singh (University of Bath) ⊠ ps2106@bath.ac.uk ⊕ www.pranavsingh.co.uk ⊙ @denoising ® @brownadder

7 Mar 2024

Applied and Computational Analysis (ACA) seminar University of Cambridge

Solution of the Schrödinger equation,

 $\mathrm{i}\partial_t\psi\ =\ \mathrm{H}(t)\,\psi,\qquad \mathrm{H}(t)^*=\mathrm{H}(t),\qquad \psi(t)\in\mathscr{H}.$ 

Feynman, R. P. Simulating physics with computers. Int J Theor Phys 21, 467-488 (1982).

the real difficulty is this: If we had many particles, we have R particles, for example, in a system, then we would have to describe the probability of a circumstance by giving the probability to find these particles at points  $x_1, x_2, \ldots, x_R$  at the time t. That would be a description of the probability of the system. And therefore, you'd need a k-digit number for every configuration of the system, for every arrangement of the R values of x. And therefore if there are N points in space, we'd need  $N^R$  configurations.

*n*-body problems

- PDE,  $\psi \in \mathbb{C}^{N^{3n}}$  after spatial discretisation with N points in each direction,
- ODE,  $\psi \in \mathbb{C}^{2^n}$  for 2-level systems (e.g. spin systems).

# 4. QUANTUM COMPUTERS—UNIVERSAL QUANTUM SIMULATORS

The first branch, one you might call a side-remark, is, Can you do it with a new kind of computer—a quantum computer? (I'll come back to the other branch in a moment.) Now it turns out, as far as I can tell, that you can simulate this with a quantum system, with quantum computer elements.



- · Linear growth in number of qubits vs exponential in classical computing
- Simple circuits with Trotterisation (no auxiliary qubits)
- Subroutine in quantum algorithms QPE (Kitaev 95), HHL (Harrow, Hassidim, Lloyd 09)
- Every gates has underlying Hamiltonian  $\Rightarrow$  every quantum circuit is HS

## Example: spin systems

- A uniquely quantum phenomenon that has no classical counterpart.
- A type of *intrinsic angular momentum* the particle is not rotating.
- Makes a quantum particle behave like a tiny magnet with a North pole and a South pole.



- Responsible for ferromagnetism.
- The phenomenon that powers
  - magnetic resonance imaging (MRI)
  - spintronics
  - quantum computing
- Suspected to be involved in detection of Earth's magnetic field by birds (quantum biology).

For *n* interacting spins, state space is exponentially large,  $\rho \in \mathbb{C}^{2^n \times 2^n}$ .

For *n* interacting spins, state space is exponentially large,  $\rho \in \mathbb{C}^{2^n \times 2^n}$ . However, requires linear growth in qubits. For *n* interacting spins, state space is exponentially large,  $\rho \in \mathbb{C}^{2^n \times 2^n}$ . However, requires linear growth in qubits.

#### Resurgence of interest in quantum algorithms for Hamiltonian simulation.

Berry et al. 15, Low & Chuang 17, 19, Low & Wiebe 18, Smith et al. 19, Kieferova et al. 19, Berry et al. 20, Chen et al. 21, Haah et al. 21, Jin & Li 21, Jin et al. 21, Dong et al. 21,22, An et al. 22, Watkins et al. 22, Mizuta et al. 23,...

Hamiltonian simulation of two-level systems is among early candidates for demonstrating quantum advantage. (Childs et al. 18, Seetharam et al. 21).

Recent claim by IBM (using their Eagle processor, 14 June 2023):

 Kim, Eddins, Anand, Wei, van den Berg, Rosenblatt, Nayfeh, Wu, Zaletel, Temme & Kandala (2023), 'Evidence for the utility of quantum computing before fault tolerance', Nature 618, 500–505. For *n* interacting spins, state space is exponentially large,  $\rho \in \mathbb{C}^{2^n \times 2^n}$ . However, requires linear growth in qubits.

#### Resurgence of interest in quantum algorithms for Hamiltonian simulation.

Berry et al. 15, Low & Chuang 17, 19, Low & Wiebe 18, Smith et al. 19, Kieferova et al. 19, Berry et al. 20, Chen et al. 21, Haah et al. 21, Jin & Li 21, Jin et al. 21, Dong et al. 21,22, An et al. 22, Watkins et al. 22, Mizuta et al. 23,...

Hamiltonian simulation of two-level systems is among early candidates for demonstrating quantum advantage. (Childs et al. 18, Seetharam et al. 21).

Recent claim by IBM (using their Eagle processor, 14 June 2023):

 Kim, Eddins, Anand, Wei, van den Berg, Rosenblatt, Nayfeh, Wu, Zaletel, Temme & Kandala (2023), 'Evidence for the utility of quantum computing before fault tolerance', Nature 618, 500–505.

Used Trotter splitting for an Ising chain.



$$\begin{aligned} \mathcal{H}(t) &= \underbrace{\mathbf{e}(t)^{\top} \mathbb{S}}_{\mathcal{H}_{ss}(t)} + \underbrace{\frac{1}{2} \mathbb{S}^{\top} \mathcal{C} \mathbb{S}}_{\mathcal{H}_{in}} \\ &= \sum_{k=1}^{n} \sum_{\alpha \in \{X,Y,Z\}} \mathbf{e}_{k}^{\alpha}(t) \alpha_{k} + \frac{1}{2} \sum_{j,k=1}^{n} \sum_{\alpha,\beta \in \{X,Y,Z\}} \mathbf{C}_{j,k}^{\alpha,\beta} \alpha_{j} \beta_{k} \end{aligned}$$

where  $\alpha_k$  acts on kth spin only,

$$\alpha_k = \underbrace{I \otimes \cdots \otimes I}_{n-k \text{ times}} \otimes \underbrace{\alpha}_{k\text{th}} \otimes \underbrace{I \otimes \cdots \otimes I}_{k-1 \text{ times}} \quad \in \mathbb{C}^{2^n \times 2^n},$$

and  $\alpha = X, Y, Z$  are Pauli matrices,

$$X = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad Y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \quad Z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

Two-level systems: Ising chains, Kitaev models, NMR/ESR, qubits (spin, superconducting, ...)

QC

 $\partial_t u = \mathcal{A} u, \quad u(0) = u_0,$ 

exact solution given by matrix exponential

$$u(t) = \exp(t\mathcal{A})u_0 = \sum_{k=0}^{\infty} \frac{(t\mathcal{A})^k}{k!} u_0.$$

Hamiltonian simulation:

$$\mathcal{A} = -\mathrm{i}h\left(\mathbf{e}^{\top}\mathbb{S} + \frac{1}{2}\mathbb{S}^{\top}\mathbf{C}\mathbb{S}\right)$$
(1)

 $\partial_t u = \mathcal{A} u, \quad u(0) = u_0,$ 

exact solution given by matrix exponential

$$u(t) = \exp(t\mathcal{A})u_0 = \sum_{k=0}^{\infty} \frac{(t\mathcal{A})^k}{k!}u_0.$$

Hamiltonian simulation:

$$\mathcal{A} = -ih \left( \mathbf{e}^{\top} \mathbb{S} + \frac{1}{2} \mathbb{S}^{\top} \mathbf{C} \mathbb{S} \right)$$
(1)

For non-interacting spins, since  $\mathfrak{su}(2)$  is spanned by iX, iY, iZ and

$$[X, Y] = iZ, [Y, Z] = iX, [Z, X] = iY,$$

can compute exponential analytically

$$\mathbf{e}^{t\mathcal{A}} = \bigotimes_{k=1}^{n} \mathbf{e}^{-\mathbf{i}t\mathbf{e}_{k}\cdot\boldsymbol{\sigma}} = \bigotimes_{k=1}^{n} \left( \begin{array}{c} \cos\left(\frac{t\|\boldsymbol{\boldsymbol{e}}_{k}\|}{2}\right) - \mathbf{i}\mathbf{e}_{k}^{z} \frac{\sin\left(\frac{i\|\boldsymbol{\boldsymbol{e}}_{k}\|}{2}\right)}{\|\mathbf{t}\mathbf{e}_{k}\|} & (-\mathbf{i}\mathbf{e}_{k}^{z} - \mathbf{e}_{k}^{y}) \frac{\sin\left(\frac{t\|\boldsymbol{\boldsymbol{e}}_{k}\|}{2}\right)}{\|\boldsymbol{\boldsymbol{e}}_{k}\|} \\ (-\mathbf{i}\mathbf{e}_{k}^{z} + \mathbf{e}_{k}^{y}) \frac{\sin\left(\frac{i\|\boldsymbol{\boldsymbol{e}}_{k}\|}{2}\right)}{\|\boldsymbol{\boldsymbol{e}}_{k}\|} & \cos\left(\frac{t\|\boldsymbol{\boldsymbol{e}}_{k}\|}{2}\right) + \mathbf{i}\mathbf{e}_{k}^{z} \frac{\sin\left(\frac{t\|\boldsymbol{\boldsymbol{e}}_{k}\|}{2}\right)}{\|\boldsymbol{\boldsymbol{e}}_{k}\|} \end{array} \right)$$

7

 $\partial_t u = \mathcal{A} u, \quad u(0) = u_0,$ 

exact solution given by matrix exponential

$$u(t) = \exp(t\mathcal{A})u_0 = \sum_{k=0}^{\infty} \frac{(t\mathcal{A})^k}{k!} u_0.$$

Hamiltonian simulation:

$$\mathcal{A} = -ih \left( \mathbf{e}^{\top} \mathbb{S} + \frac{1}{2} \mathbb{S}^{\top} \mathbf{C} \mathbb{S} \right)$$
(1)

For non-interacting spins, since  $\mathfrak{su}(2)$  is spanned by iX, iY, iZ and

$$[X, Y] = iZ, \quad [Y, Z] = iX, \quad [Z, X] = iY,$$

can compute exponential analytically

$$\mathbf{e}^{t\mathcal{A}} = \bigotimes_{k=1}^{n} \mathbf{e}^{-\mathbf{i}t\mathbf{e}_{k}\cdot\boldsymbol{\sigma}} = \bigotimes_{k=1}^{n} \left( \begin{array}{c} \cos\left(\frac{t\|\boldsymbol{\boldsymbol{e}}_{k}\|}{2}\right) - \mathbf{i}\mathbf{e}_{k}^{z} \frac{\sin\left(\frac{\|\boldsymbol{\boldsymbol{e}}_{k}\|}{2}\right)}{\|\mathbf{t}\mathbf{e}_{k}\|} & (-\mathbf{i}\mathbf{e}_{k}^{z} - \mathbf{e}_{k}^{y}) \frac{\sin\left(\frac{t\|\boldsymbol{\boldsymbol{e}}_{k}\|}{2}\right)}{\|\boldsymbol{\boldsymbol{e}}_{k}\|} \\ (-\mathbf{i}\mathbf{e}_{k}^{z} + \mathbf{e}_{k}^{y}) \frac{\sin\left(\frac{t\|\boldsymbol{\boldsymbol{e}}_{k}\|}{2}\right)}{\|\boldsymbol{\boldsymbol{e}}_{k}\|} & \cos\left(\frac{t\|\boldsymbol{\boldsymbol{e}}_{k}\|}{2}\right) + \mathbf{i}\mathbf{e}_{k}^{z} \frac{\sin\left(\frac{t\|\boldsymbol{\boldsymbol{e}}_{k}\|}{2}\right)}{\|\boldsymbol{\boldsymbol{e}}_{k}\|} \end{array} \right)$$

**Trotterisation**: For -iH = A + B we need to split

$$\exp(h(A+B)) = e^{hA}e^{hB} + \mathcal{O}(h^2)$$

QC

7

## Trotterisation:

$$\mathrm{e}^{-\mathrm{i} h (\mathcal{H}^X + \mathcal{H}^Y + \mathcal{H}^Z)} = \mathrm{e}^{-\mathrm{i} h \mathcal{H}^X} \mathrm{e}^{-\mathrm{i} h \mathcal{H}^Y} \mathrm{e}^{-\mathrm{i} h \mathcal{H}^Z} + \mathcal{O}\Big(h^2\Big)\,,$$

where

$$\mathcal{H}^{\alpha} = \mathbf{e}^{\top} \mathbb{S}^{\alpha} + \frac{1}{2} \mathbb{S}^{\alpha \top} \boldsymbol{C}^{\alpha, \alpha} \mathbb{S}^{\alpha}, \qquad \alpha \in \{X, Y, Z\},$$

and

$$\mathrm{e}^{-\mathrm{i}h\mathcal{H}^{\alpha}} = \prod_{\ell=1}^{n} \mathrm{e}^{-\mathrm{i}h\mathbf{e}_{\ell}^{\alpha}\alpha_{\ell}} \prod_{j=1}^{n} \prod_{k=j+1}^{n} \mathrm{e}^{-\mathrm{i}h\mathbf{C}_{j,k}^{\alpha,\alpha}\alpha_{j}\alpha_{k}},$$

computed exactly using *n* single-qubit gates and  $O(n^2)$  coupling gates.



QC

If  $e^{hA}$  and  $e^{hB}$  are easier to compute, approximate  $e^{h(A+B)}$  by

splitting	error	name	stages
e <sup>hA</sup> e <sup>hB</sup>	$\mathcal{O}(h^2)$	Trotter	2

If  $e^{hA}$  and  $e^{hB}$  are easier to compute, approximate  $e^{h(A+B)}$  by

splitting	error	name	stages
e <sup>hA</sup> e <sup>hB</sup>	$O(h^2)$	Trotter	2
$e^{\frac{1}{2}hB}e^{hA}e^{\frac{1}{2}hB}$	$O(h^3)$	Strang	3
$\mathrm{e}^{a_1hB}\mathrm{e}^{b_1hA}\mathrm{e}^{a_2hB}\ldots\mathrm{e}^{b_nhA}\ldots\mathrm{e}^{a_2hB}\mathrm{e}^{b_1hA}\mathrm{e}^{a_1hB}$	$\mathcal{O}(h^{2p+1})$	Classical	$\mathcal{O}(2^p)$
$e^{\frac{h}{6}A}e^{\frac{h}{2}B}e^{\frac{2}{3}(hA+\frac{h^3}{48}[[A,B],B])}e^{\frac{h}{2}B}e^{\frac{h}{6}A}$	$\mathcal{O}(h^{2p+1})$	Compact	$\mathcal{O}(2^p)$
$\mathrm{e}^{\frac{h}{2}\boldsymbol{B}}\mathrm{e}^{\frac{h}{2}\boldsymbol{A}}\mathrm{e}^{h^{3}\boldsymbol{R}}\mathrm{e}^{h^{5}\boldsymbol{S}}\mathrm{e}^{h^{3}\boldsymbol{R}}\mathrm{e}^{\frac{h}{2}\boldsymbol{A}}\mathrm{e}^{\frac{h}{2}\boldsymbol{B}}$	$\mathcal{O}\!\left(h^{2p+1} ight)$	Asymptotic	$\mathcal{O}(p)$

Yoshida 1990, Murua & Sanz-Serna 1999, Chin & Chen 2002, McLachlan & Quispel 2002, Blanes, Casas & Murua 2008, Chartier & Murua 2009, ... Asymptotic (Zassenhaus) Bader, Iserles, Kropielnicka, & S. 2014, Found. Comp. Math.

#### High order splittings



No good reason to use Trotter instead of Strang, even for NISQ Chen, Foroozandeh, Budd & S. 2023. *Quantum simulation of highly-oscillatory many-body Hamiltonians for near-term devices*, submitted 'Evidence for the utility of quantum computing before fault tolerance' IBM paper appeared on 14 June 2023.

'Evidence for the utility of quantum computing before fault tolerance' IBM paper appeared on 14 June 2023.

Classical algorithms appeared on 26 and 28 June 2023.

- Tindall, Fishman, Stoudenmire & Sels, 'Efficient tensor network simulation of IBMs kicked lsing experiment'
- Begušić & Chan, 'Fast classical simulation of evidence for the utility of quantum computing before fault tolerance'. Computed on a single core of a laptop!

'Evidence for the utility of quantum computing before fault tolerance' IBM paper appeared on 14 June 2023.

Classical algorithms appeared on 26 and 28 June 2023.

- Tindall, Fishman, Stoudenmire & Sels, 'Efficient tensor network simulation of IBMs kicked lsing experiment'
- Begušić & Chan, 'Fast classical simulation of evidence for the utility of quantum computing before fault tolerance'. Computed on a single core of a laptop!



Dulwich Quantum Computing @DulwichOuantum

••

At least 7 articles so far have reproduced the @IBM computation classically: arxiv.org/abs/2306.14887 arxiv.org/abs/2306.15970 arxiv.org/abs/2306.16372 arxiv.org/abs/2308.01339 arxiv.org/abs/2308.03082 arxiv.org/abs/2308.05077 arxiv.org/abs/2308.09109 BQP (bounded-error quantum polynomial time)

Class of decision problems solvable by a quantum computer in polynomial time, with an error probability of at most 1/3 for all instances.

 $\mathsf{P}\subseteq\mathsf{BQP}\subseteq\mathsf{PSPACE}$ 

BQP (bounded-error quantum polynomial time)

Class of decision problems solvable by a quantum computer in polynomial time, with an error probability of at most 1/3 for all instances.

 $\mathsf{P}\subseteq\mathsf{BQP}\subseteq\mathsf{PSPACE}$ 

 $P \stackrel{?}{=} BQP \stackrel{?}{=} PSPACE$  is not known.

The only 'definitive' proof of quantum 'supremacy' (in Hamiltonian simulation or otherwise) is to show BQP  $\neq$  P.



Splitting, Diagonalisation, Scaling and Squaring

	Asymptotic	Approximate $e^z$ on spectrum	Iterative
	z  ightarrow 0	$z\in [a,b]\subseteq \sigma(A)$	Use A and u0
	Taylor	Chebyshev	
Polynomial	$\sum_{k=0}^{n} \frac{z^k}{k!}$	$J_0(i) + 2 \sum_{k=1}^{n} i^k J_k(-i) T_k(z)$	Lanczos
Rational	$\frac{Padé}{\frac{1+\frac{1}{2}z+\frac{1}{12}z^2}{1-\frac{1}{2}z+\frac{1}{12}z^2}}$	?	Rational Krylov

Qubitization (Low & Chuang 2019) based on Chebyshev.

Splitting, Diagonalisation, Scaling and Squaring

	Asymptotic	Approximate $e^z$ on spectrum	Iterative
	z  ightarrow 0	$z\in [a,b]\subseteq \sigma(A)$	Use A and u0
	Taylor	Chebyshev	
Polynomial	$\sum_{k=0}^{n} \frac{z^k}{k!}$	$J_0(i) + 2 \sum_{k=1}^{n} i^k J_k(-i) T_k(z)$	Lanczos
Rational	$\frac{Padé}{\frac{1+\frac{1}{2}z+\frac{1}{12}z^2}{1-\frac{1}{2}z+\frac{1}{12}z^2}}$	?	Rational Krylov

Qubitization (Low & Chuang 2019) based on Chebyshev.

Unitarity:  $|\exp(ix)| = 1$ , exp maps imaginary axis to unit circle.

Splitting, Diagonalisation, Scaling and Squaring

	Asymptotic	Approximate $e^z$ on spectrum	Iterative
	z  ightarrow 0	$z\in [a,b]\subseteq \sigma(A)$	Use A and u0
	Taylor	Chebyshev	
Polynomial	$\sum_{k=0}^{n} \frac{z^k}{k!}$	$J_0(i) + 2 \sum_{k=1}^{n} i^k J_k(-i) T_k(z)$	Lanczos
Rational	$\frac{Padé}{\frac{1+\frac{1}{2}z+\frac{1}{12}z^2}{1-\frac{1}{2}z+\frac{1}{12}z^2}}$	?	Rational Krylov

Qubitization (Low & Chuang 2019) based on Chebyshev.

Unitarity:  $|\exp(ix)|=1$ , exp maps imaginary axis to unit circle. Since  $\sigma(iH) \subseteq i\mathbb{R}$ ,

 $|f(\mathbf{i}x)| = 1$   $x \in \mathbb{R}$   $\implies$   $f(\mathbf{i}H)$  is unitary

Splitting, Diagonalisation, Scaling and Squaring

	Asymptotic	Approximate $e^z$ on spectrum	Iterative
	z  ightarrow 0	$z\in [a,b]\subseteq \sigma(A)$	Use A and u0
	Taylor	Chebyshev	
Polynomial	$\sum_{k=0}^{n} \frac{z^k}{k!}$	$J_0(i) + 2 \sum_{k=1}^{n} i^k J_k(-i) T_k(z)$	Lanczos
Rational	$\frac{Padé}{\frac{1+\frac{1}{2}z+\frac{1}{12}z^2}{1-\frac{1}{2}z+\frac{1}{12}z^2}}$	?	Rational Krylov

Qubitization (Low & Chuang 2019) based on Chebyshev.

Unitarity:  $|\exp(ix)| = 1$ , exp maps imaginary axis to unit circle. Since  $\sigma(iH) \subseteq i\mathbb{R}$ ,

 $|f(\mathbf{i}x)| = 1$   $x \in \mathbb{R}$   $\implies$   $f(\mathbf{i}H)$  is unitary

No non-constant polynomial method can be unitary. Proof: coercivity.

#### Schrödinger equation



exp maps Lie algebra  $iH \in \mathfrak{su}(n)$  to Lie group  $e^{-itH} \in U(n)$ .

#### Schrödinger equation



exp maps Lie algebra  $iH \in \mathfrak{su}(n)$  to Lie group  $e^{-itH} \in U(n)$ .

These properties are also desired from numerical approximations.

Wave, KdV, NLS, Pauli, Dirac, Liouville-von Neumann, Linblad, MCTDHF, CCSD, TDDFT, ...

## Uniform approximation with AAA & AAA-Lawson

- AAA. Nakatsukasa, Sète & Trefethen. The AAA algorithm for rational approximation, SIAM J. Sci. Comput., Vol. 40, Iss. 3 (2018).
- AAA–Lawson. Nakatsukasa & Trefethen. An algorithm for real and complex rational minimax approximation, SIAM J. Sci. Comput., Vol. 4, Iss. 5 (2020).





AAA and AAA–Lawson methods are adaptive algorithms that can produce rational approximants with uniform accuracy over a specified interval or test nodes  $x_k$ .

## Uniform approximation with AAA & AAA-Lawson

- AAA. Nakatsukasa, Sète & Trefethen. The AAA algorithm for rational approximation, SIAM J. Sci. Comput., Vol. 40, Iss. 3 (2018).
- AAA–Lawson. Nakatsukasa & Trefethen. An algorithm for real and complex rational minimax approximation, SIAM J. Sci. Comput., Vol. 4, Iss. 5 (2020).





AAA and AAA–Lawson methods are adaptive algorithms that can produce rational approximants with uniform accuracy over a specified interval or test nodes  $x_k$ .

$$r(x) = \underbrace{\sum_{j=1}^{m} \frac{\mathrm{e}^{\mathrm{i} y_j} \, w_j}{x - y_j}}_{n(x)} \Big/ \underbrace{\sum_{j=1}^{m} \frac{w_j}{x - y_j}}_{d(x)} \approx \mathrm{e}^{\mathrm{i} x},$$

linearize and minimize

$$\|L\mathbf{w}\|_{2} = \Big(\sum_{k=1}^{n} \mu_{k} |n(x_{k}) - e^{ix_{k}} d(x_{k})|^{2}\Big)^{1/2}$$

Computed using SVD of Loewner matrix,  $L_{kj} = \mu_k^{1/2} \frac{e^{ix_k} - e^{iy_j}}{x_k - y_j}$ , and picking w as the right singular vector corresponding to the smallest singular value.

## Loewner matrix based rational approximations and interpolations are unitary.

Jawecki & S 2023. Unitarity of some barycentric rational approximants, IMA J. Num. Anal.

Includes Antoulas & Anderson 1986, Mayo & Antoulas 2007, NST 2018 (AAA), NT 2020 (AAA–Lawson), JS (*submitted*) (interpolation at Chebyshev nodes, modified BRASIL algorithm, modified AAA–Lawson), ...

## Loewner matrix based rational approximations and interpolations are unitary. Jawecki & S 2023. Unitarity of some barycentric rational approximants, IMA J. Num. Anal.

Includes Antoulas & Anderson 1986, Mayo & Antoulas 2007, NST 2018 (AAA), NT 2020 (AAA–Lawson), JS (submitted) (interpolation at Chebyshev nodes, modified BRASIL algorithm, modified AAA–Lawson), ...



Modified AAA and AAA-Lawson (JS 23) ensures unitarity to machine precision.

#### Wavefunction centred around two different energy levels

$$u_0(x) = \psi_1(x) + \psi_2(x), \qquad \psi_j(x) = \sum_{k=0}^n c_{j,k} v_k(x), \quad c_{j,k} = e^{-(\mu_j - \lambda_k)^2/2\sigma_j^2}$$

Error in approximation of  $e^{ix}$ (AAA–Lawson)



Wavefunction centred around two different energy levels

$$u_0(x) = \psi_1(x) + \psi_2(x), \qquad \psi_j(x) = \sum_{k=0}^n c_{j,k} v_k(x), \quad c_{j,k} = e^{-(\mu_j - \lambda_k)^2/2\sigma_j^2}$$

Error in approximation of  $e^{ix}$ (AAA–Lawson) Error in matrix approximation  $r(-ihH)u_0$ ((31,31) AAA–Lawson vs Padé)



Jawecki & S. in preparation

#### **Best approximation**

Approximating  $f \in C([a, b]; \mathbb{R})$  in  $\mathcal{P}_n[a, b]$ 

• Best approximant  $p^* \in \mathcal{P}_n$  exists & unique

$$\|f-p^*\|_{\infty}=\inf\{\|f-p\|_{\infty}: p\in \mathcal{P}_n\},\$$

• Chebyshev equioscillation theorem

$$f(x_j) - p^*(x_j) = (-1)^{j+\iota} ||f - p||_{\infty}, \qquad \iota \in \{0, 1\}$$

- Remez minimax algorithm
  - Find points  $\{x_j\}$  of local maximum error  $|f(x) p^{[k]}(x)|$ .
  - Stop if equioscillation property satisfied.
  - Otherwise, solve for  $f(x_j) p^{[k+1]}(x_j) = (-1)^j E$

#### **Best approximation**

Approximating  $f \in C([a, b]; \mathbb{R})$  in  $\mathcal{P}_n[a, b]$ 

• Best approximant  $p^* \in \mathcal{P}_n$  exists & unique

$$\|f-p^*\|_{\infty}=\inf\{\|f-p\|_{\infty}: p\in \mathcal{P}_n\},\$$

• Chebyshev equioscillation theorem

$$f(x_j) - p^*(x_j) = (-1)^{j+\iota} ||f - p||_{\infty}, \qquad \iota \in \{0, 1\}$$

- Remez minimax algorithm
  - Find points  $\{x_i\}$  of local maximum error  $|f(x) p^{[k]}(x)|$ .
  - Stop if equioscillation property satisfied.
  - Otherwise, solve for  $f(x_j) p^{[k+1]}(x_j) = (-1)^j E$

Motivates AAA–Lawson minimax algorithm [NT20] for approximating  $f \in C(I \subseteq \mathbb{C}; \mathbb{C})$  in  $\mathcal{R}_n[I] = \left\{ \frac{p}{q} : p, q \in \mathcal{P}_n \right\}$  (or in Barycentric forms).

• Gives good approximants in practice (typically), but ...

#### **Best approximation**

Approximating  $f \in C([a, b]; \mathbb{R})$  in  $\mathcal{P}_n[a, b]$ 

• Best approximant  $p^* \in \mathcal{P}_n$  exists & unique

$$\|f-p^*\|_{\infty}=\inf\{\|f-p\|_{\infty}: p\in \mathcal{P}_n\},\$$

• Chebyshev equioscillation theorem

$$f(x_j) - p^*(x_j) = (-1)^{j+\iota} ||f - p||_{\infty}, \qquad \iota \in \{0, 1\}$$

- Remez minimax algorithm
  - Find points  $\{x_i\}$  of local maximum error  $|f(x) p^{[k]}(x)|$ .
  - Stop if equioscillation property satisfied.
  - Otherwise, solve for  $f(x_j) p^{[k+1]}(x_j) = (-1)^j E$

Motivates AAA–Lawson minimax algorithm [NT20] for approximating  $f \in C(I \subseteq \mathbb{C}; \mathbb{C})$  in  $\mathcal{R}_n[I] = \left\{ \frac{p}{q} : p, q \in \mathcal{P}_n \right\}$  (or in Barycentric forms).

- Gives good approximants in practice (typically), but ...
- No best approximation results for complex-valued rational approximation,
- $\{p \in \mathcal{P}_n : \|p\|_{\infty} = 1\}$  is compact,  $\{r \in \mathcal{R}_n : \|r\|_{\infty} = 1\}$  is not compact,
- No equioscillation property in C.

## Equioscillation

#### Figures from [NT20]

(left)  $f(z) = e^z$  on  $\{z \in \mathbb{C} : |z|=1\}$ (right) f(z) = Ai(z) on  $z \in [-10, 10]$ 

deviation f(z) - r(z) & max error ||f - r||No equioscillation!



## Equioscillation

#### Figures from [NT20]

(left)  $f(z) = e^z$  on  $\{z \in \mathbb{C} : |z|=1\}$ (right) f(z) = Ai(z) on  $z \in [-10, 10]$ 

deviation f(z) - r(z) & max error ||f - r||No equioscillation!



$$f(\mathrm{i}x) = \mathrm{e}^{\mathrm{i}\omega x}, \quad x \in [-1, 1]$$

18 June (left), T. Jawecki 28 June (right), N. Trefethen

Rose curves with 2n petals. equioscillation?

## Equioscillation

#### Figures from [NT20]

(left)  $f(z) = e^z$  on  $\{z \in \mathbb{C} : |z| = 1\}$ (right) f(z) = Ai(z) on  $z \in [-10, 10]$ 

deviation f(z) - r(z) & max error ||f - r||No equioscillation!



$$f(\mathrm{i}x) = \mathrm{e}^{\mathrm{i}\omega x}, \quad x \in [-1, 1]$$

18 June (left), T. Jawecki 28 June (right), N. Trefethen

Rose curves with 2n petals. equioscillation?

Let  $r(ix) = e^{ig(x)}$ , where g(x) is phase Optimality  $\iff$  phase equioscillates

$$g(x_j) - \omega x_j = (-1)^{j+\iota} \max_{x \in [-1,1]} |g(x) - \omega x|.$$
  
$$|r(ix_j) - e^{i\omega x_j}| = ||r - \exp(\omega \cdot)||$$

Zeros of phase & approx error coincide.



0

-0

Jawecki & S 2023. Unitary rational best approximations to the exponential function, submitted.

**Theorem.** For  $\omega \in (0, (n + 1)\pi)$ , there exists a unique unitary best approximation  $r \in U_n$ , i.e.,

$$\|\boldsymbol{r} - \exp(\boldsymbol{\omega} \cdot)\| = \inf_{\boldsymbol{u} \in \mathcal{U}_n} \|\boldsymbol{u} - \exp(\boldsymbol{\omega} \cdot)\|, \qquad \|\boldsymbol{f}\| := \sup_{\boldsymbol{x} \in [-1,1]} |\boldsymbol{f}(\mathbf{i}\boldsymbol{x})|,$$

whose phase error equioscillates at 2n + 2 points, where max approx error is achieved. Moreover, r has minimal degree n, and distinct poles.

Jawecki & S 2023. Unitary rational best approximations to the exponential function, submitted.

**Theorem.** For  $\omega \in (0, (n + 1)\pi)$ , there exists a unique unitary best approximation  $r \in U_n$ , i.e.,

$$\|r - \exp(\omega \cdot)\| = \inf_{u \in \mathcal{U}_n} \|u - \exp(\omega \cdot)\|, \qquad \|f\| := \sup_{x \in [-1,1]} |f(\mathbf{i}x)|,$$

whose phase error equioscillates at 2n + 2 points, where max approx error is achieved. Moreover, r has minimal degree n, and distinct poles.

Superlinear convergence. For  $\omega < 1.47(n+1/2)$ ,

$$\min_{u\in\mathcal{U}_n}\|u-\exp(\omega\cdot)\|\leq \frac{(n!)^2\omega^{2n+1}}{(2n)!(2n+1)!}.$$

(proof via Pade),

Jawecki & S 2023. Unitary rational best approximations to the exponential function, submitted.

**Theorem.** For  $\omega \in (0, (n + 1)\pi)$ , there exists a unique unitary best approximation  $r \in U_n$ , i.e.,

$$\|r - \exp(\omega \cdot)\| = \inf_{u \in \mathcal{U}_n} \|u - \exp(\omega \cdot)\|, \qquad \|f\| := \sup_{x \in [-1,1]} |f(\mathbf{i}x)|,$$

whose phase error equioscillates at 2n + 2 points, where max approx error is achieved. Moreover, r has minimal degree n, and distinct poles.

Superlinear convergence. For  $\omega < 1.47(n+1/2)$ ,

$$\min_{u \in \mathcal{U}_n} \|u - \exp(\omega \cdot)\| \le \frac{(n!)^2 \omega^{2n+1}}{(2n)! (2n+1)!}.$$

(proof via Pade), and in the limit  $\omega \rightarrow 0^+$ ,

$$\min_{u \in \mathcal{U}_n} \|u - \exp(\omega \cdot)\| = \frac{2(n!)^2}{(2n)! (2n+1)!} \left(\frac{\omega}{2}\right)^{2n+1} + \mathcal{O}(\omega^{2n+2}), \quad \omega \to 0^+.$$

(proof via interpolation at Chebyshev points), twice as fast as Padé.

Poles,  $\omega 
ightarrow 0^+$ ,  $\omega 
ightarrow (n+1)\pi^-$ 



In the limit  $\omega \rightarrow 0^+$ , poles converge to poles of Padé.

In the limit  $\omega \to (n+1)\pi^-$ , poles approach  $i\xi_j$ , where  $\xi_j = -1 + 2j/(n+1)$  for j = 1, ..., n, within the right-half complex plane.

Poles,  $\omega 
ightarrow 0^+$ ,  $\omega 
ightarrow (n+1)\pi^-$ 



In the limit  $\omega \rightarrow 0^+$ , poles converge to poles of Padé.

In the limit  $\omega \to (n+1)\pi^-$ , poles approach  $i\xi_j$ , where  $\xi_j = -1 + 2j/(n+1)$  for j = 1, ..., n, within the right-half complex plane.

A-stability. Poles of best approximants are in right half plane and

|r(z)| < 1, for  $z \in \mathbb{C}$  with  $\operatorname{Re}(z) < 0$ .

Relevant for non-Hermitian matrices/operators (e.g. open systems).

Time-symmetric.

$$r(-\mathrm{i}x) = r(\mathrm{i}x)^{-1}, \quad x \in \mathbb{R}.$$

## Interpolation and equioscillation points, $\omega \to 0^+$ , $\omega \to (n+1)\pi^-$



In the limit  $\omega \rightarrow 0^+$ , interpolation points converge to Chebyshev nodes.

In the limit  $\omega \to (n+1)\pi^-$ , interpolation points and equioscillation points converge to uniformly distributed points. Phase error approaches sawtooth function.

Three new algorithms. Interpolation at Chebyshev points, modified AAA–Lawson and BRASIL algorithms – latter two candidates for best approximation (seem to display equioscillatory behaviour).



**Figure 1:** [new] unitary best approximation ( $\blacksquare$ ), error estimate (dashed, +), [new] rational interpolant at Chebyshev nodes ( $\triangleright$ ), Padé approximation ( $\circ$ ), Padé error bound (dashed,  $\times$ ), polynomial Chebyshev approximation ( $\nabla$ ), rational Chebyshev approximation ( $\triangle$ ), .

#### C. Moler & C. V. Loan, Nineteen Dubious Ways to Compute the Exponential of a Matrix,

Twenty-Five Years Later, SIAM Review (2003).

	Asymptotic	Approximate $e^z$ on spectrum	Iterative
	z  ightarrow 0	$\pmb{z} \in [\pmb{a}, \pmb{b}] \subseteq \sigma(\pmb{A})$	Use $A$ and $u_0$
	Taylor	Chebyshev	
Polynomial	$\sum_{k=0}^{n} \frac{z^{k}}{k!}$	$J_0(i) + 2 \sum_{k=1}^{n} i^k J_k(-i) T_k(z)$	Lanczos
	Padé		
Rational	$\frac{1 + \frac{1}{2}z + \frac{1}{12}z^2}{1 - \frac{1}{2}z + \frac{1}{12}z^2}$	unitary best approximations	Rational Krylov

Other techniques: Diagonalisation, Spectral methods, Scaling and Squaring, Splitting

AAA [NST 18], AAA–Lawson [NT 20], their unitary modifications [JS 23], and three new algorithms [JS submitted].

- Jawecki & S. 2023. Unitarity of some barycentric rational approximants, IMA J. Num. Anal.
- Jawecki & S. 2023. Unitary rational best approximations to the exponential function, submitted.
- Jawecki & S., in preparation.

## Driven systems – Is Magnus expansion DoA?

The solution to 
$$u'(t) = \mathcal{A}(t)u(t)$$
,  $\mathcal{A}(t) = -iH(t)$ ,  
 $u(h) = \exp(\Theta(h))u_0$ ,

where  $\Theta(h)$  is the Magnus expansion [Magnus 54],

$$\Theta(h) = \int_0^h \mathcal{A}(\xi) \, \mathrm{d}\xi - \frac{1}{2} \int_0^h \int_0^{\xi} [\mathcal{A}(\zeta), \mathcal{A}(\xi)] \, \mathrm{d}\zeta \, \mathrm{d}\xi \quad \longleftarrow \text{ Fourth order}$$
$$+ \frac{1}{12} \int_0^h \int_0^{\xi} \int_0^{\xi} [\mathcal{A}(\chi), [\mathcal{A}(\zeta), \mathcal{A}(\xi)]] \, \mathrm{d}\chi \, \mathrm{d}\zeta \, \mathrm{d}\xi$$
$$+ \frac{1}{4} \int_0^h \int_0^{\xi} \int_0^{\zeta} [[\mathcal{A}(\chi), \mathcal{A}(\zeta)], \mathcal{A}(\xi)] \, \mathrm{d}\chi \, \mathrm{d}\zeta \, \mathrm{d}\xi + \dots$$
$$\mathcal{A}(t) = -\mathrm{iH}(t), \quad \mathrm{H}(t) = \sum_{k=1}^n \sum_{\alpha \in \{X, Y, Z\}} \mathrm{e}_k^{\alpha}(t) \, \alpha_k + \frac{1}{2} \sum_{i,k=1}^n \sum_{\alpha \in \{X, Y, Z\}} \frac{\mathcal{C}_{j,k}^{\alpha, \beta}}{\mathcal{C}_{j,k}^{\alpha, \beta}} \, \alpha_j \, \beta_k$$

 $|C| \leq O(n^2)$  terms

 $\mathcal{O}(n)$  terms

#### Driven systems – Is Magnus expansion DoA?

The solution to 
$$u'(t) = \mathcal{A}(t)u(t)$$
,  $\mathcal{A}(t) = -iH(t)$ ,  
 $u(h) = \exp(\Theta(h))u_0$ ,

where  $\Theta(h)$  is the Magnus expansion [Magnus 54],

 $\mathcal{A}($ 

$$\Theta(h) = \int_{0}^{h} \mathcal{A}(\xi) d\xi - \frac{1}{2} \int_{0}^{h} \int_{0}^{\xi} [\mathcal{A}(\zeta), \mathcal{A}(\xi)] d\zeta d\xi \quad \longleftarrow \text{ Fourth order}$$
$$+ \frac{1}{12} \int_{0}^{h} \int_{0}^{\xi} \int_{0}^{\xi} [\mathcal{A}(\chi), [\mathcal{A}(\zeta), \mathcal{A}(\xi)]] d\chi d\zeta d\xi$$
$$+ \frac{1}{4} \int_{0}^{h} \int_{0}^{\xi} \int_{0}^{\zeta} [[\mathcal{A}(\chi), \mathcal{A}(\zeta)], \mathcal{A}(\xi)] d\chi d\zeta d\xi + \dots$$
$$t) = -iH(t), \quad H(t) = \sum_{k=1}^{n} \sum_{\alpha \in I[X, X]} e_{k}^{\alpha}(t) \alpha_{k} + \frac{1}{2} \sum_{i, k=1}^{n} \sum_{\alpha \in I[X, X]} C_{i,k}^{\alpha, \beta} \alpha_{j} \beta_{k}$$

 $\mathcal{O}(n) \text{ terms} \qquad |C| \leq \mathcal{O}(n^2) \text{ terms}$ **Issue:**  $\mathcal{A}$  has  $\mathcal{O}(|C|) = \mathcal{O}(n^2)$  terms. Does  $\Theta_2$  have  $\mathcal{O}(|C|^2) = \mathcal{O}(n^4)$  terms?

#### A standard method for classical computers, infeasible for quantum computers.

Instead, other approaches used: Dyson series (Kieferova et al. 2019), time-ordered operators (Watkins et al. 2022), L1 norm scaling (Berry et al. 2020), permutation expansion (Chen et al. 2021), slowly varying Hamiltonians (Haah et al. 2021), interaction picture (Low & Wiebe 2018), Floquet approach (Mizuta et al. 2023).

## Driven systems – Is Magnus expansion DoA? No!

Theorem (Fourth order Magnus based circuit)



Chen, Foroozandeh, Budd & S. 2023. submitted

For two controls: Ikeda, Abrar, Chuang & Sugiura 2023. Quantum.



In fact, Magnus is much better than all other methods! Time-dependent problems of practical interest are MUCH harder! Maximize fidelity:

$$heta^* = \operatorname*{argmax}_{ heta} \, \mathcal{F}( heta)$$

Fidelity functions

$$\mathcal{F}(\boldsymbol{\theta}) = f(\mathbf{U}(T; \boldsymbol{\theta}))$$

where state of system is  $\rho(t) = \mathbf{U}(t; \theta)\rho_0$ .



Maximize fidelity:

$$\theta^* = \operatorname*{argmax}_{\theta} \mathcal{F}(\theta)$$

Fidelity functions

$$\mathcal{F}(\boldsymbol{\theta}) = f(\mathbf{U}(T; \boldsymbol{\theta}))$$

where state of system is  $\rho(t) = \mathbf{U}(t; \theta)\rho_0$ .



Local optimization: need gradients

$$\frac{\partial \mathcal{F}}{\partial \theta} = \mathsf{D}f(\mathsf{U}(T;\theta))\frac{\partial \mathsf{U}(T;\theta)}{\partial \theta}$$

and Hessians.

- No dissipation
- Piecewise constant

$$\mathbf{U}(T;\theta) = \mathrm{U}_N \mathrm{U}_{N-1} \cdots \mathrm{U}_2 \mathrm{U}_1, \quad \text{with} \quad \mathrm{U}_n = \mathrm{e}^{-\mathrm{i} \boldsymbol{s}_n \cdot \boldsymbol{\sigma}}, \quad \boldsymbol{s}_n := h \boldsymbol{e}(t_n).$$

We can store intermediate propagators

$$\mathbf{L}_n := \mathbf{U}_N \mathbf{U}_{N-1} \dots \mathbf{U}_n, \qquad \mathbf{R}_n := \mathbf{U}_n \mathbf{U}_{n-1} \dots \mathbf{U}_1, \qquad \mathcal{O}(N)$$

to compute gradients cheaply and exactly

$$\frac{\partial \mathbf{U}}{\partial \theta_{n,k}} = \mathbf{L}_{n+1} \frac{\partial \mathbf{U}_n}{\partial \theta_{n,k}} \mathbf{R}_{n-1}, \qquad \frac{\partial \mathbf{U}_n}{\partial \theta_{n,k}} = -\mathrm{i} \mathbf{U}_n \left( \begin{bmatrix} \mathbf{D}_n \frac{\partial \mathbf{s}_n}{\partial \theta_{n,k}} \end{bmatrix} \cdot \boldsymbol{\sigma} \right),$$
$$\mathbf{D}_n = \sum_{p=0}^{\infty} \frac{(-\mathbf{s}_n)^p}{(p+1)!} = I + c_1 \mathbf{s}_n + c_2 \mathbf{s}_n^2, \qquad \mathbf{s}_n = \begin{pmatrix} 0 & -s_{n,z} & s_{n,y} \\ s_{n,z} & 0 & -s_{n,x} \\ -s_{n,y} & s_{n,x} & 0 \end{pmatrix}.$$

$$\mathbf{M}_{n,m} := \mathbf{U}_n \mathbf{U}_{n-1} \dots \mathbf{U}_{m+1} \mathbf{U}_m. \qquad \mathcal{O}(N^2)$$

and use for computing  $\frac{\partial^2 U}{\partial \theta_{m,j} \partial \theta_{n,k}} = \mathrm{L}_{n+1} \frac{\partial \mathrm{U}_n}{\partial \theta_{n,k}} \mathrm{M}_{n-1,m+1} \frac{\partial \mathrm{U}_m}{\partial \theta_{m,j}} \mathrm{R}_{m-1}.$ 

$$\mathbf{M}_{n,m} := \mathbf{U}_{n}\mathbf{U}_{n-1}\ldots\mathbf{U}_{m+1}\mathbf{U}_{m}. \qquad \mathcal{O}\left(\boldsymbol{N}^{2}\right)$$

and use for computing  $\frac{\partial^2 U}{\partial \theta_{m,j} \partial \theta_{n,k}} = L_{n+1} \frac{\partial U_n}{\partial \theta_{n,k}} M_{n-1,m+1} \frac{\partial U_m}{\partial \theta_{m,j}} R_{m-1}$ . We exploit the unitarity of  $U_k$ , i.e.  $U_k^* U_k = I$ , to note that

 $\mathbf{M}_{n,m} = \left(\mathbf{U}_{N} \dots \mathbf{U}_{n+1}\right)^{*} \mathbf{U}_{N} \dots \mathbf{U}_{n+1} \mathbf{M}_{n,m} \mathbf{U}_{m-1} \dots \mathbf{U}_{1} \left(\mathbf{U}_{m-1} \dots \mathbf{U}_{1}\right)^{*}$ 

$$\mathbf{M}_{n,m} := \mathbf{U}_{n}\mathbf{U}_{n-1}\ldots\mathbf{U}_{m+1}\mathbf{U}_{m}. \qquad \mathcal{O}\left(\mathbf{N}^{2}\right)$$

and use for computing  $\frac{\partial^2 U}{\partial \theta_{m,j} \partial \theta_{n,k}} = L_{n+1} \frac{\partial U_n}{\partial \theta_{n,k}} M_{n-1,m+1} \frac{\partial U_m}{\partial \theta_{m,j}} R_{m-1}$ . We exploit the unitarity of  $U_k$ , i.e.  $U_k^* U_k = I$ , to note that

 $\mathrm{M}_{n,m} = (\mathrm{U}_N \ldots \mathrm{U}_{n+1})^* \mathrm{U}_N \ldots \mathrm{U}_{n+1} \mathrm{M}_{n,m} \mathrm{U}_{m-1} \ldots \mathrm{U}_1 (\mathrm{U}_{m-1} \ldots \mathrm{U}_1)^* = \mathrm{L}_n^* \textbf{U} \mathrm{R}_m^*,$ 

$$\mathbf{M}_{n,m} := \mathbf{U}_{n}\mathbf{U}_{n-1}\ldots\mathbf{U}_{m+1}\mathbf{U}_{m}. \qquad \mathcal{O}\left(\mathbf{N}^{2}\right)$$

and use for computing  $\frac{\partial^2 U}{\partial \theta_{m,j} \partial \theta_{n,k}} = L_{n+1} \frac{\partial U_n}{\partial \theta_{n,k}} M_{n-1,m+1} \frac{\partial U_m}{\partial \theta_{m,j}} R_{m-1}$ . We exploit the unitarity of  $U_k$ , i.e.  $U_k^* U_k = I$ , to note that

 $\mathbf{M}_{n,m} = (\mathbf{U}_N \dots \mathbf{U}_{n+1})^* \mathbf{U}_N \dots \mathbf{U}_{n+1} \mathbf{M}_{n,m} \mathbf{U}_{m-1} \dots \mathbf{U}_1 (\mathbf{U}_{m-1} \dots \mathbf{U}_1)^* = \mathbf{L}_n^* \mathbf{U} \mathbf{R}_m^*,$ 

so that entries of the Hessian can be computed as  $L_{n+1} \frac{\partial U_n}{\partial \theta_{n,k}} L_n^* \mathbf{U} R_m^* \frac{\partial U_m}{\partial \theta_{m,j}} R_{m-1}$ .

$$\mathbf{M}_{n,m} := \mathbf{U}_{n}\mathbf{U}_{n-1}\ldots\mathbf{U}_{m+1}\mathbf{U}_{m}. \qquad \mathcal{O}\left(\boldsymbol{N}^{2}\right)$$

and use for computing  $\frac{\partial^2 U}{\partial \theta_{m,j} \partial \theta_{n,k}} = L_{n+1} \frac{\partial U_n}{\partial \theta_{n,k}} M_{n-1,m+1} \frac{\partial U_m}{\partial \theta_{m,j}} R_{m-1}$ . We exploit the unitarity of  $U_k$ , i.e.  $U_k^* U_k = I$ , to note that

 $\mathbf{M}_{n,m} = (\mathbf{U}_{N} \dots \mathbf{U}_{n+1})^* \mathbf{U}_{N} \dots \mathbf{U}_{n+1} \mathbf{M}_{n,m} \mathbf{U}_{m-1} \dots \mathbf{U}_1 (\mathbf{U}_{m-1} \dots \mathbf{U}_1)^* = \mathbf{L}_n^* \mathbf{U} \mathbf{R}_m^*,$ so that entries of the Hessian can be computed as  $\mathbf{L}_{n+1} \frac{\partial \mathbf{U}_n}{\partial \theta_{n,k}} \mathbf{L}_n^* \mathbf{U} \mathbf{R}_m^* \frac{\partial \mathbf{U}_m}{\partial \theta_{m,i}} \mathbf{R}_{m-1}.$ 



Speedup:  $\times 2 - 10$  fidelity,  $\times 4 - 30$  gradient,  $\times 20 - 600$  Hessian.

Foroozandeh & S. 2022. Automatica. ESCALADE doi:10.17632/8zz84359m5 Goodwin & Vinding 2023. Phys. Rev. Res.

#### Coupling, dissipation & adaptive optimal control

Liouville-von Neumann equation, piecewise constant,

$$\partial_t \rho = \mathcal{L}(t; \theta) \rho, \qquad \mathcal{L}_n(\theta) = \underbrace{-\mathrm{i} \operatorname{ad}_{\mathbf{e}(t_n; \theta)^\top \mathbb{S}}}_{\mathcal{L}_n^{[1]}(\theta)} \quad \underbrace{-\mathrm{i} \operatorname{ad}_{\operatorname{Hin} + \mathcal{R}}}_{\mathcal{L}^{[2]}}$$

Splittings  $S_{(1)}, S_{(2)}, \ldots, S_{(L)} \approx U(T; \theta)$  with increasing accuracies,

$$U_n = e^{h\mathcal{L}_n(\theta)} \approx \prod_{k=1}^{K} \underbrace{e^{ha_k \mathcal{L}_n^{[1]}(\theta)}}_{\text{uncoupled, analytic grad}} e^{hb_k \mathcal{L}^{[2]}}$$

 $\text{Move from } \mathcal{S}_{(\ell)} \text{ to } \mathcal{S}_{(\ell+1)} \text{ when } |\mathcal{F}_{(\ell)} - \mathcal{F}_{(\ell+1)}| \hspace{1.5cm} \leq \hspace{1.5cm} \kappa_{\mathcal{F}} |1 - \mathcal{F}_{(\ell)}|$ 



Goodwin, Foroozandeh & S. 2022. Science Advances. QOALA github.com/superego101/qoala

## Takeaways & Open Problems

- Quantum Computing. [1] Chen, Foroozandeh, Budd & S. 2023. Quantum simulation of highly-oscillatory many-body Hamiltonians for near-term devices, submitted
  - No good reason to use Trotter (used in IBM paper) instead of Strang.
  - Practical time-dependent problems are much harder, high order methods required.
  - Magnus methods are not DoA, in fact, lead to shortest circuits even for 10<sup>-1</sup> accuracy.
  - \* Better splittings? Better commutator-free methods?
- Approximation Theory. [2] Jawecki & S. 2023. Unitarity of some barycentric rational approximants, IMA J. Num. Anal. [3] Jawecki & S. 2023. Unitary rational best approximations to the exponential function, submitted. [4] Jawecki & S., in prep.
  - Loewner based algorithms (incl. AAA) conserve unitarity, energy, norm
  - Unitary rational best approximations exist, unique & phase equioscillates
  - Three new algorithms (Cheb. interp., AAA–Lawson at Cheb., modified BRASIL), AAA/AAA–Lawson, all superior to existing rational approximations.
  - \* Rational best approximations to  $e^{i\omega x} =$ Unitary rational best approximations?
  - \* Observed twice faster convergence than Padé. Proof for non-asymptotic  $\omega$ ?
  - \* Does modified BRASIL converge to best approximation?
- Optimal Control. [5] Foroozandeh & S. 2022. Optimal control of spins by Analytical Lie Algebraic Derivatives, Automatica. ESCALADE doi:10.17632/8zz84359m5. [6] Goodwin, Foroozandeh & S. 2022. Adaptive optimal control of entangled qubits, Science Advances. QOALA github.com/superego101/qoala. [7] Sherzad, Chen, Foroozandeh & S., in prep.
  - Compute analytic gradients using Lie algebraic techniques.
  - Hessian factorization reduces cost from  $\mathcal{O}(N^2)$  to  $\mathcal{O}(N)$ , x20 600 speedup.
  - Use cheaper method far from optima, switch adaptively.
  - \* Are pulses robust under timing and amplitude imperfections?

#### Temporary page!

Let TEX was unable to guess the total number of pages correctly. As there was some unprocessed data that should have been added to the final page this extra page has been added to receive it.

If you rerun the document (without altering it) this surplus page will go away because PTEX now knows how many pages to expect for this document.